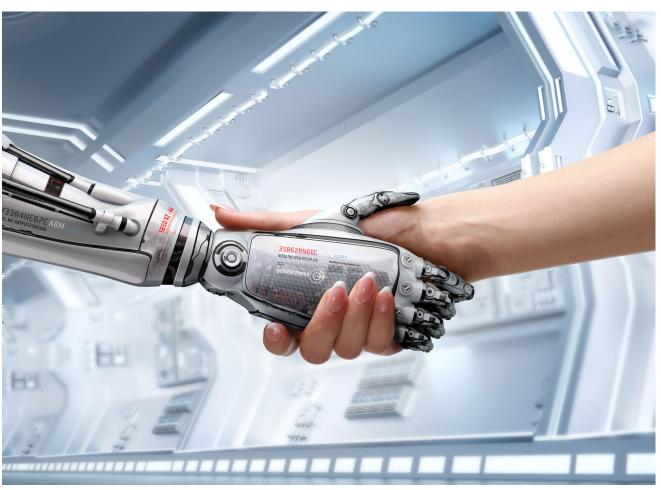
Utilizing a human centered design approach for mine automation

Pilot project update

Dr. Mahiyar Nasarwanji Dr. Lisa Steiner Dr. Brianna Eiter

Automation Partnership Meeting September 14-15, 2022



NIOSH Mining Program



Defining Human Centered (centred) Design

"Human-centred design is an *approach*

to interactive *systems development*

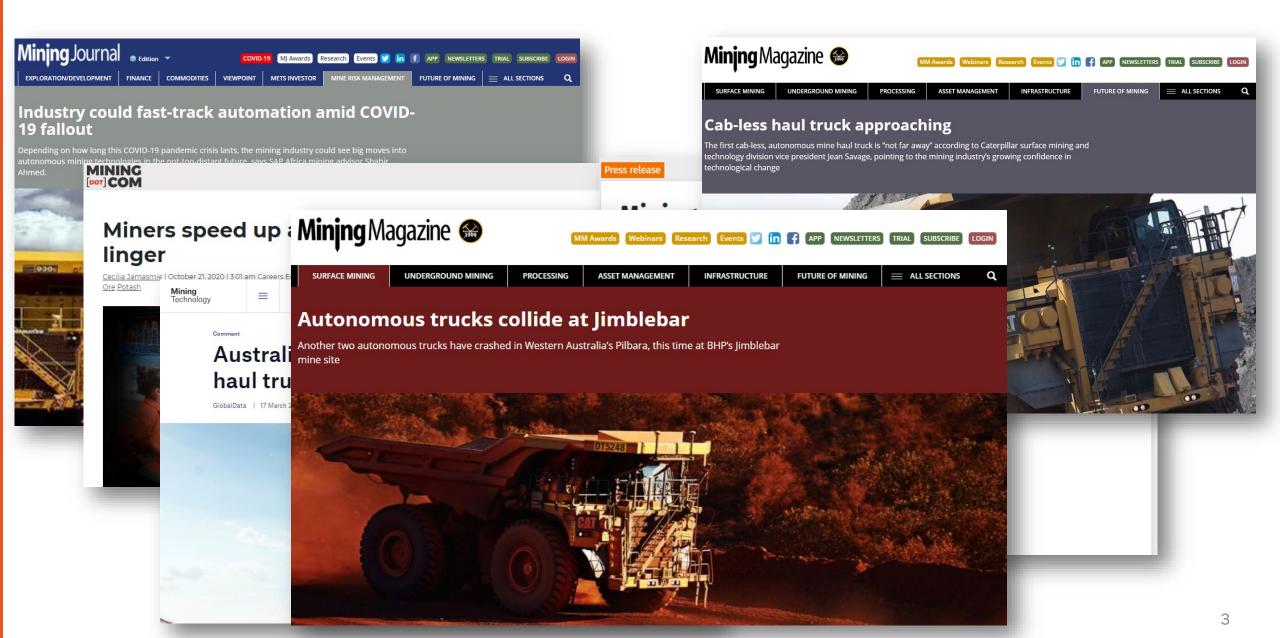
that aims to *make systems usable and useful*

by focusing on the users, their needs and requirements, and

by applying *human factors/ergonomics, and*

usability knowledge and techniques."

Automation at mines is increasing



Research objective

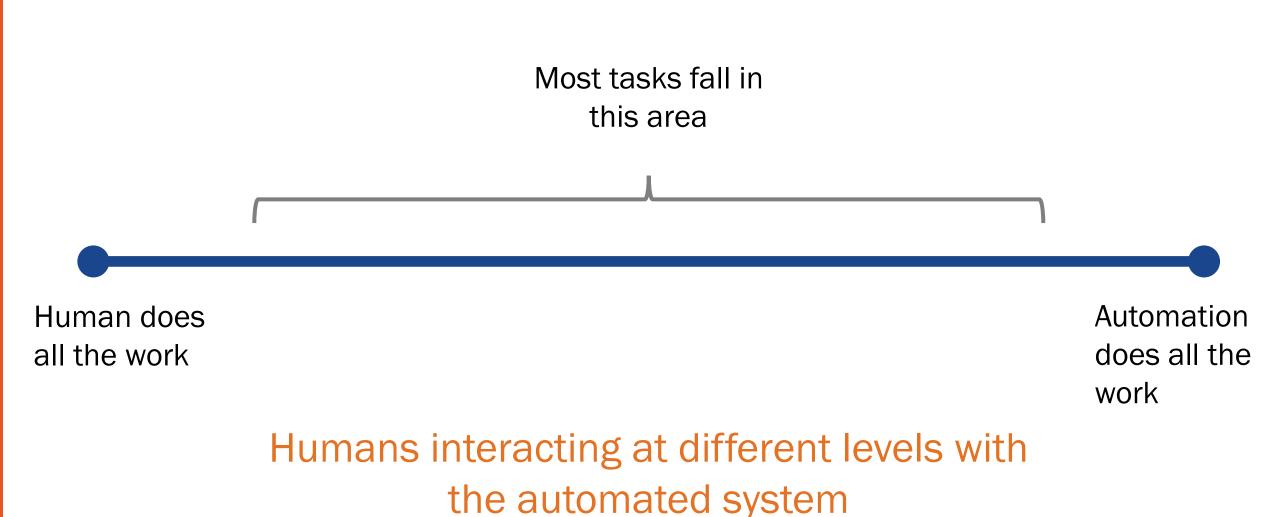
 To identify, understand, and document human factors considerations and expectations when designing, deploying, and implementing automation along its continuum as part of a human system integrated approach to improve mineworker's health and safety.



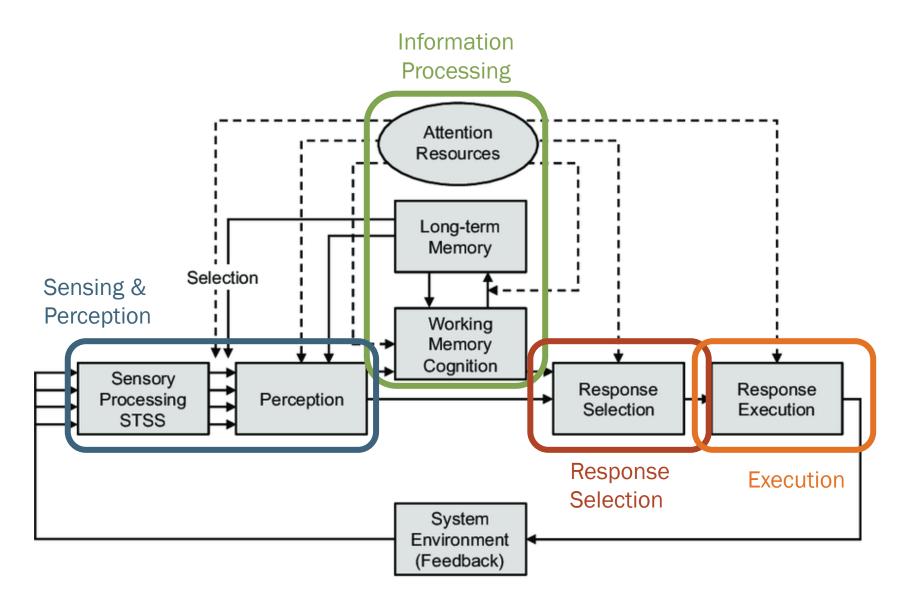
Until we can design truly independent systems humans will be involved and need to interact with the system



The continuum of automation



Human information processing model



Adapted from Wickens, C. D., & Flach, J. M. (1988). Information processing. Human factors in aviation, 111-155.

Simple human information processing model



Levels of automation in the human context (based on decision making and response selection and execution)

1. Manual	The human performs all the required tasks.
2. Action Support	System assists the operator with performance of the selected action (eg tele-operation).
3. Batch Processing	Human generates and selects options to be performed, which are turned over to the system to be carried out automatically.
4. Shared Control	Both human and system generate possible decision options, human selects which option to implement, carrying out actions is shared.
5. Decision Support	The system automatically generates a list of decision options, human selects from list or generates own, then turned over to system to implement.
6. Blended Decision Making	The system automatically generates a list of decision options, which it selects from and carries out if human consents.
7. Rigid System	The system presents a limited set of actions to the human, human must select from list, the system will then implement the actions.
8. Automated Decision Making	The system selects the best option (from a system and human generated list) and implements it.
9. Supervisory Control	The system generates options, selects and implements the option, human monitors and intervenes if required, who can select a different option.
10. Full Automation	The system carries out all actions, human completely out of control loop and cannot intervene.

Kaber, D. B., & Endsley, M. R. (2004). The effects of level of automation and adaptive automation on human performance, situation awareness and workload in a dynamic control task. *Theoretical Issues in Ergonomics Science*, *5*(2), 113-153.

Taxonomies

	Level charac- teristic Authors	Sheridan & Verplanck [63,65] (10 LOA)	Endsley [13] (4 LOA)	Ntuen & Park [39,40] (5 LOA)	Riley [55] (12 LOA)	Miligram [35] <mark>(5 LOA)</mark>	Endsley & Kiris [15] (5 LOA)	Draper [12] <mark>(5 LOA)</mark>	Endsley & Kaber [14] (10 LOA)	Lorenz et al. [32] (3 LOA)	Clough [8] (4 LOA)	Proud et al. [54] (8LOA)	Fereidunian et al. [16,17] (11 LOA)
	Manual (a)	Level 1		Level 1	Level 1	Level 1	Level 1	Level 1	Level 1	Level 1 (Low Level)	Level 1	Level 1	Level 0
	Data Acquisition (b)				Level 2 (Information Fuser)							Level 2	Level 1
	Telepresence (c)					Level 2							
	Manual Control with intelligent Assistance (d)							Level 2					
	Remotely Operated (e)										Level 2 (Remotely Operated)		
	Computer offers decisions (f)	Level 2	Level 1 (Decision Support)	Level 2 (Decision Support)	Level 3 (Simple Aid)		Level 2		Level 2 (Action support)	Level 2 (Medium Level)		Level 3	Level 2
	Narrows down selection (g)	Level 3							Level 7 (Rigid system)				Level 3
	Director/Agent Control (h)				Levels 4,5,6 (Advisor, Interactive/ Adaptive Advisor)	Level 3 (Director/Agent Control)			Level 3 (Batch Processing)				
Levels	Shared Control (i)							Level 3	Level 4 (Shared Control)				
	Suggests one alternative (j)	Level 4											Level 4
	Executes with human approval (k)	Level 5	Level 2 (Conceptual AI)	Level 3 (Conceptual Al)	Levels 7,8 (Servant, Assistant)		Level 3		Level 6 (Blended Decision Making)			Level 4	Level 5
	Decision Support (I)								Level 5		Level 3 (Remotely Supervised)		
	Executes if no human veto (m)	Level 6	Level 3 (Monitored AI)	Level 4 (Monitored AI)			Level 4			Level 3 (High Level)		Level 5	Level 6
	Executes and informs human (n)	Level 7			Level 9 (Associate)							Level 6	Level 7
	Partner (o)				Level 10			Level 4 (Traded Control)					
	Informs human if asked (p)	Level 8										Level 7	Level 8
)	Informs human, if decides (q)	Level 9							Level 8 (Automated Decision making)				Level 9
	Supervisor (r)				Level 11	Level 4		Level 5	Level 9				
	Autonomous System (s)	Level 10	Level 4	Level 5	Level 12	Level 5	Level 5		Level 10		Level 4	Level 8	Level 10

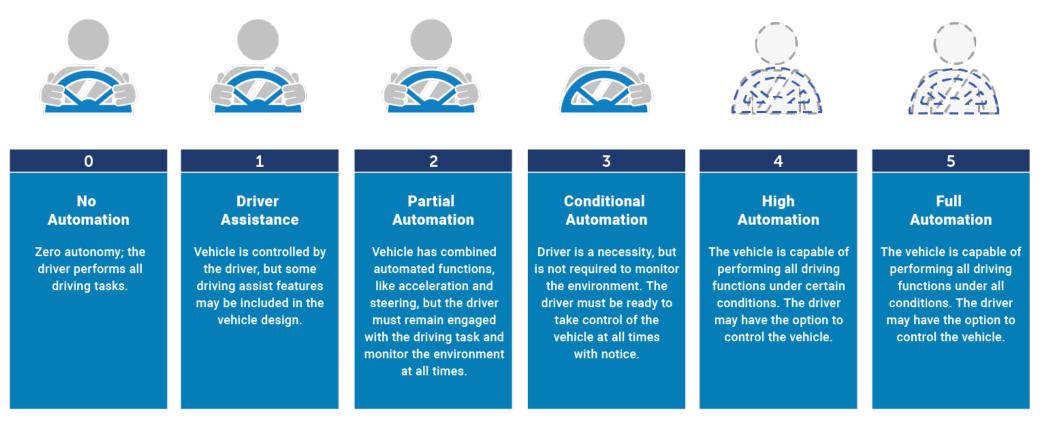
Lots of different taxonomies with lots of different levels

Vagia, M., Transeth, A. A., & Fjerdingen, S. A. (2016). A literature review on the levels of automation during the years. What are the different taxonomies that have been proposed?. *Applied ergonomics*, *53*, 190-202.

In general, taxonomies are decision support and action based

- Full manual control
- Decision support where the automated system provides
 - Information \rightarrow Human decides what to do
 - Response options (potentially prioritized) \rightarrow Human decides which option they want
- Limited action where the automated system provides
 - One option \rightarrow Human has to approve action (consent)
 - One option \rightarrow Human can veto
- Automatic action
 - Human informed of action
 - Human can ask for information on action
 - Human out of the loop

Example of levels of automation for self driving cars



https://www.nhtsa.gov/technology-innovation/automated-vehicles-safety

The focus is on the technology

SAE J3016 Levels of		SAE LEVEL O™	SAE LEVEL 1™	SAE LEVEL 2™	SAE LEVEL 3™	SAE LEVEL 4™	SAE LEVEL 5™		
Driving	What does the human in the driver's seat have to do?		nenever these driver su if your feet are off the p not steering		You <u>are not</u> driving when these automated driving features are engaged – even if you are seated in "the driver's seat"				
Automation			antly supervise these er, brake or accelerate maintain safety		When the feature requests, you must drive	requests, will not require you to take			
		These are	driver suppor	t features	These are automated driving features				
	What do these features do?	These features are limited to providing warnings and momentary assistance	These features provide steering OR brake/ acceleration support to the driver	These features provide steering AND brake/ acceleration support to the driver	under limited con operate unless al	These features can drive the vehicle under limited conditions and will not operate unless all required conditions are metThis feature can drive the vehicle under all conditions			
INTERNATIONAL ®	Example Features	 automatic emergency braking blind spot warning lane departure warning 	 lane centering OR adaptive cruise control 	 lane centering AND adaptive cruise control at the same time 	• traffic jam chauffeur	 local driverless taxi pedals/ steering wheel may or may not be installed 	 same as level 4, but feature can drive everywhere in all conditions 		

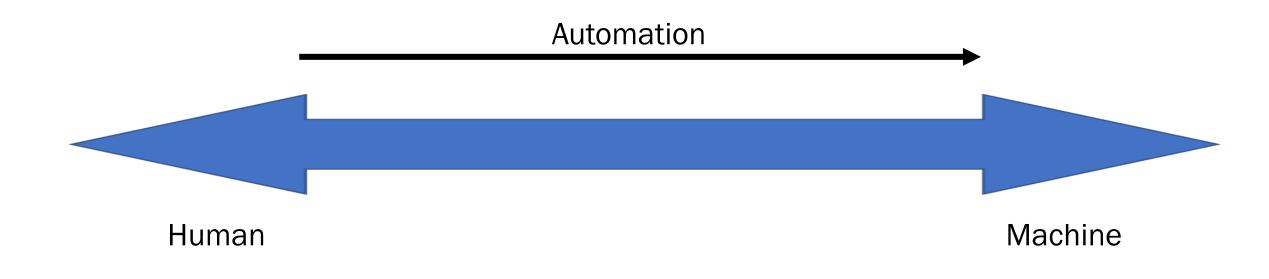
Merging capability with reliability

Automation Capability

		Machine capability	Sensing	Computation / analysis	Programmed / learned decision	Motor Action
	Machine reliability	Human	Sensing & Perception	Information processing	Response selection	Execution
	No automation	Full human control	x	Х	X	x
l	Assistance	Provide information to human	$\checkmark\checkmark$	\checkmark	\checkmark	x
l	Partial automation	Constant human attention	$\sqrt{\sqrt{2}}$	$\checkmark\checkmark$	$\checkmark\checkmark$	$\checkmark\checkmark$
l	Supervisory	Human attention at request	VVV	$\sqrt{\sqrt{2}}$	$\sqrt{\sqrt{2}}$	VVV
	Conditional	Independent except in predefined conditions	\ \\\	\ \\	$\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{$	\ \\\
V	Full	Independent	<i>\\\\\</i>	$\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{$	$\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{\sqrt{$	~~~~

This is not the end

• Still need to combine this into a single continuum.



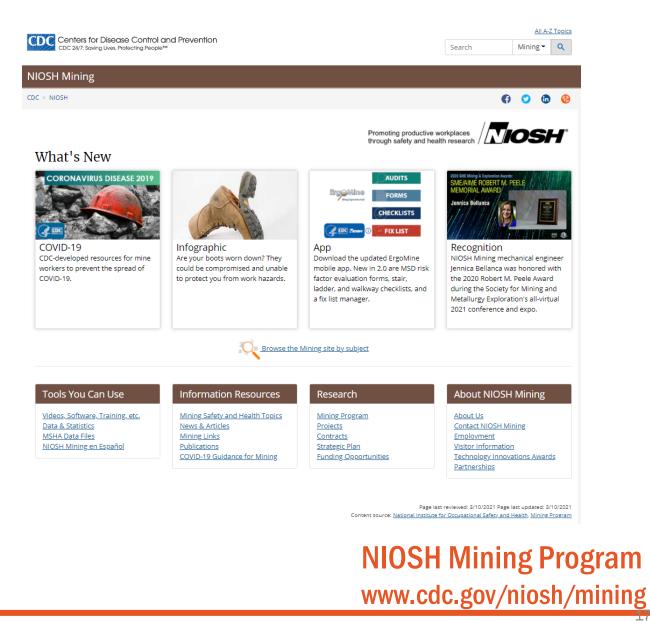
Preliminary human factors considerations

- Based on literature
 - Trust
 - Acceptance of technology
 - Overreliance
 - Situation awareness
 - Boredom associated with vigilance
 - Skill degradation



Thank you!

Mahiyar Nasarwanji, PhD, CPE <u>MNasarwanji@cdc.gov</u> (412) 386-5113





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